

This script accompanies the paper *Inequalities à la Pólya for the Aharonov–Bohm eigenvalues of the disk* by N. Filonov, M. Levitin, I. Polterovich, and D. A. Sher, see Proposition 3.8

For rigorous verified rational approximations proofs of some inequalities appearing in the text see the end of the script

Preliminaries

```
In[3]:= h[x_] := 1 / Pi (Sqrt[1 - x^2] - x ArcCos[x]);  
G[λ_, z_] := λ h[z / λ];  
Wdisk[d_, λ_] := (λ / 2) ^ d Gamma[1 + d / 2] ^ (-2);
```

Verified approximations

```
In[6]:= CosUp[x_] := 1 -  $\frac{x^2}{2} + \frac{x^4}{24} - \frac{x^6}{720} + \frac{x^8}{40320} - \frac{x^{10}}{3628800} + \frac{x^{12}}{479001600}$ ;  
CosDown[x_] := 1 -  $\frac{x^2}{2} + \frac{x^4}{24} - \frac{x^6}{720} + \frac{x^8}{40320} - \frac{x^{10}}{3628800} + \frac{x^{12}}{479001600} - \frac{x^{14}}{87178291200}$ ;  
VerifiedQUpArcCos[x_, ε_] := Module[{ac0, ac},  
  ac0 = ArcCos[x];  
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,  
    ac = Rationalize[ac0 + 2 ε, ε];  
    If[CosUp[ac] ≥ x, Message[VerifiedQUpArcCos::Error, x], ac];  
  (* ac=Rationalize[ArcCos[x]+2ε,ε]; *)  
  ac  
];  
VerifiedQUpArcCos::Error = "ArcCosUp of argument `1` is wrong!";
```

```

VerifiedQDownArcCos[x_, ε_] := Module[{ac0, ac},
  ac0 = ArcCos[x];
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,
    ac = Rationalize[ac0 - 2 ε, ε];
    If[CosDown[ac] ≤ x, Message[VerifiedQDownArcCos::Error, x], ac]];
  ac
];
VerifiedQDownArcCos::Error = "ArcCosDown of argument `1` is wrong!";
VerifiedQUpSqrt[x_, ε_] := Module[{ac0, ac},
  ac0 = Sqrt[x];
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,
    ac = Rationalize[ac0 + 2 ε, ε];
    If[ac^2 < x, Message[VerifiedQUpSqrt::Error, x], ac]];
  ac
];
VerifiedQUpSqrt::Error = "SqrtUp of argument `1` is wrong!";
VerifiedQDownSqrt[x_, ε_] := Module[{ac0, ac},
  ac0 = Sqrt[x];
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,
    ac = Rationalize[ac0 - 2 ε, ε];
    If[ac^2 > x, Message[VerifiedQDownSqrt::Error, x], ac]];
  ac
];
VerifiedQDownSqrt::Error = "SqrtDown of argument `1` is wrong!";
VerifiedQUpRoot[x_, d_, ε_] := Module[{ac0, ac},
  ac0 = x^(1/d);
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,
    ac = Rationalize[ac0 + 2 ε, ε];
    If[ac^d < x, Message[VerifiedQUpRoot::Error, x], ac]];
  ac
];
VerifiedQUpRoot::Error = "RootUp `2` of argument `1` is wrong!";
VerifiedQDownRoot[x_, d_, ε_] := Module[{ac0, ac},
  ac0 = x^(1/d);
  If[MatchQ[ac0, _Rational] || IntegerQ[ac0], ac = ac0,
    ac = Rationalize[ac0 - 2 ε, ε];
    If[ac^d > x, Message[VerifiedQDownRoot::Error, x], ac]];
  ac
];
VerifiedQDownSqrt::Error = "RootDown `2` of argument `1` is wrong!";

```

Algorithm

```

In[20]:= PiUp[ε_] := 3 VerifiedQUpArcCos[1/2, ε];
PiDown[ε_] := 3 VerifiedQDownArcCos[1/2, ε];
GQDown[λ_, z_, ε_] := If[z > λ, 0,
  (VerifiedQDownSqrt[λ^2 - z^2, ε] - z VerifiedQUpArcCos[z/λ, ε]) / PiUp[ε]];
WdiskQUp[d_, λ_, ε_] := Wdisk[d, λ] /. Pi → PiDown[ε];
adisk[d_, ε_] := WdiskQUp[d, λ, ε] / λ^d;
PABNeuQDown[λ_, ε_] := Total[Table[Floor[GQDown[λ, m + 1/2, ε] + 3/4] +
  Floor[GQDown[λ, m + 1, ε] + 3/4], {m, 0, Ceiling[λ] - 1}]];

In[26]:= StepCheckAB[λ_, ε_] := Module[{e, λnew},
  e = PABNeuQDown[λ, ε] - WdiskQUp[2, λ, ε];
  If[e ≤ 0, Print["Process stopped with e=", e]; Return[]];
  λnew = VerifiedQDownRoot[λ^2 + e / adisk[2, ε], 2, ε];
  {λ, λ // N, e, e // N, λnew, λnew // N}
];

RunChecksAB[Δstart_, Δend_, ε_, printstep_] := Module[{Δ, nI, data, step},
  data = {};
  nI = 1;
  Δ = Δstart;
  Do[
    step = StepCheckAB[Δ, ε];
    If[printstep, Print[step]];
    AppendTo[data, step];
    If[step[[5]] ≤ Δ, Break[]];
    Δ = step[[5]];
    If[Δ ≥ Δend, Break[]];
    ,
    {nI, 1, 100 000}
  ];
  step = StepCheckAB[Δ, ε];
  If[printstep, Print[step]];
  AppendTo[data, step];
  data
];

```

Actual Calculation

```

In[28]:= Δ20short = 5 / 2;
Δ21short = 9;
data2dshort = RunChecksAB[Δ20short, Δ21short, 10^(-3), True];
tb2short = Table[{j, data2dshort[[j, 1]],
  data2dshort[[j, 3]], data2dshort[[j, 5]] - data2dshort[[j, 1]]},
  {j, 1, Length[data2dshort]}] // TableForm

```

$$\left\{ \frac{5}{2}, 2.5, \frac{7}{16}, 0.4375, \frac{65}{23}, 2.82609 \right\}$$

$$\left\{ \frac{65}{23}, 2.82609, \frac{2123}{2116}, 1.00331, \frac{45}{13}, 3.46154 \right\}$$

$$\left\{ \frac{45}{13}, 3.46154, \frac{679}{676}, 1.00444, 4, 4. \right\}$$

$$\left\{ 4, 4., 1, 1., \frac{76}{17}, 4.47059 \right\}$$

$$\left\{ \frac{76}{17}, 4.47059, \frac{290}{289}, 1.00346, \frac{142}{29}, 4.89655 \right\}$$

$$\left\{ \frac{142}{29}, 4.89655, \frac{846}{841}, 1.00595, \frac{164}{31}, 5.29032 \right\}$$

$$\left\{ \frac{164}{31}, 5.29032, \frac{964}{961}, 1.00312, \frac{164}{29}, 5.65517 \right\}$$

$$\left\{ \frac{164}{29}, 5.65517, \frac{1686}{841}, 2.00476, \frac{196}{31}, 6.32258 \right\}$$

$$\left\{ \frac{196}{31}, 6.32258, \frac{1928}{961}, 2.00624, \frac{187}{27}, 6.92593 \right\}$$

$$\left\{ \frac{187}{27}, 6.92593, \frac{5855}{2916}, 2.00789, \frac{202}{27}, 7.48148 \right\}$$

$$\left\{ \frac{202}{27}, 7.48148, \frac{1463}{729}, 2.00686, 8, 8. \right\}$$

$$\left\{ 8, 8., 2, 2., \frac{246}{29}, 8.48276 \right\}$$

$$\left\{ \frac{246}{29}, 8.48276, \frac{1691}{841}, 2.0107, \frac{313}{35}, 8.94286 \right\}$$

$$\left\{ \frac{313}{35}, 8.94286, \frac{14731}{4900}, 3.00633, \frac{374}{39}, 9.58974 \right\}$$

$$\left\{ \frac{374}{39}, 9.58974, \frac{4577}{1521}, 3.0092, \frac{418}{41}, 10.1951 \right\}$$

Out[31]//TableForm=

1	$\frac{5}{2}$	$\frac{7}{16}$	$\frac{15}{46}$
2	$\frac{65}{23}$	$\frac{2123}{2116}$	$\frac{190}{299}$
3	$\frac{45}{13}$	$\frac{679}{676}$	$\frac{7}{13}$
4	4	1	$\frac{8}{17}$
5	$\frac{76}{17}$	$\frac{290}{289}$	$\frac{210}{493}$
6	$\frac{142}{29}$	$\frac{846}{841}$	$\frac{354}{899}$
7	$\frac{164}{31}$	$\frac{964}{961}$	$\frac{328}{899}$
8	$\frac{164}{29}$	$\frac{1686}{841}$	$\frac{600}{899}$
9	$\frac{196}{31}$	$\frac{1928}{961}$	$\frac{505}{837}$
10	$\frac{187}{27}$	$\frac{5855}{2916}$	$\frac{5}{9}$
11	$\frac{202}{27}$	$\frac{1463}{729}$	$\frac{14}{27}$
12	8	2	$\frac{14}{29}$
13	$\frac{246}{29}$	$\frac{1691}{841}$	$\frac{467}{1015}$
14	$\frac{313}{35}$	$\frac{14731}{4900}$	$\frac{883}{1365}$
15	$\frac{374}{39}$	$\frac{4577}{1521}$	$\frac{968}{1599}$

Verifying some inequalities

$$\sqrt{3} + \frac{6}{5\pi} - \frac{5\pi}{9} > 0, \text{ page 10}$$

In[33]:= VerifiedQDownSqrt[3, 10^(-3)] + 6 / (5 PiUp[10^(-3)]) - 5 PiUp[10^(-3)] / 9

Out[33]=

$$\frac{395}{1092}$$

$$\frac{5\pi}{6} < 2\sqrt{2}, \text{ page 10}$$

In[34]:= 5 / 6 PiUp[10^(-3)] - 2 VerifiedQDownSqrt[2, 10^(-3)]

Out[34]=

$$-\frac{27}{136}$$

$q_2\left(\frac{783}{1000}\right) > q_1\left(\frac{783}{1000}\right) > 3$, page 14

```
In[35]:= c0 = 783 / 1000;
q2Down = 1 / (3481 / 2500 - 4 / PiUp[10^(-5)]);
q1Up = PiUp[10^(-5)] / (4 ( VerifiedQDownSqrt[1 - c0^2, 10^(-5)] -
    c0 VerifiedQUpArcCos[c0, 10^(-5)]));
q1Down = PiDown[10^(-5)] / (4 ( VerifiedQUpSqrt[1 - c0^2, 10^(-5)] -
    c0 VerifiedQDownArcCos[c0, 10^(-5)]));
q2Down - q1Up
q1Down - 3
```

```
Out[39]=
  21 748 540 846 500
  -----
  91 065 923 628 253
```

```
Out[40]=
  593 657
  -----
  115 381
```